

Comment on Sakurai problem 1.29(a)¹

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1 November 2009

We would like to show that

$$[\hat{x}_i, G(\hat{\mathbf{p}})] = i \frac{\partial G(\hat{\mathbf{p}})}{\partial p_i} , \quad (1)$$

where the hats here indicate operators. The right hand side is the partial derivative of $G(\mathbf{p})$ with respect to p_i , with the numbers p_1 , p_2 and p_3 then replaced by operators \hat{p}_1 , \hat{p}_2 and \hat{p}_3 . There is a second part, for $[\hat{p}_i, F(\hat{\mathbf{x}})]$, but this is really the same problem, just with x and p interchanged. There are two ways to do this problem.

First, let's try it with just operators, using the power series expansion of G ,

$$G(\hat{\mathbf{p}}) = \sum_{n_1, n_2, n_3} g(n_1, n_2, n_3) \hat{p}_1^{n_1} \hat{p}_2^{n_2} \hat{p}_3^{n_3} . \quad (2)$$

Note the form of this. A typical term might be $g(1, 3, 2) \hat{p}_1 \hat{p}_2^3 \hat{p}_3^2$. We need to commute this with one of the \hat{x} components. Let's say it is \hat{x}_1 . Now \hat{x}_1 commutes with all of the components \hat{p}_j except for \hat{p}_1 . We have

$$[\hat{x}_1, \hat{p}_1^{n_1}] = i n_1 \hat{p}_1^{n_1-1} . \quad (3)$$

(To prove this, you just commute \hat{x}_1 past each factor of \hat{p}_1 . Note that there is a factor $i = \sqrt{-1}$ in addition to the index i .) With this result, we have

$$[\hat{x}_1, G(\hat{\mathbf{p}})] = i \sum_{n_1, n_2, n_3} n_1 g(n_1, n_2, n_3) \hat{p}_1^{n_1-1} \hat{p}_2^{n_2} \hat{p}_3^{n_3} . \quad (4)$$

This is the power series expansion of $\partial G(\hat{\mathbf{p}})/\partial p_1$. Thus

$$[\hat{x}_1, G(\hat{\mathbf{p}})] = i \frac{\partial G(\hat{\mathbf{p}})}{\partial p_1} . \quad (5)$$

The same proof holds for $i = 2$ and $i = 3$. Thus we arrive at the result that we wanted.

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Second, we can apply the operator we wanted to a wave function. We consider $\langle \mathbf{p} | [\hat{x}_i, G(\hat{\mathbf{p}})] | \psi \rangle$ and use the known result for the action of \hat{x}_i on a momentum space wave function, then we use the rule for differentiating a product:

$$\begin{aligned}
\langle \mathbf{p} | [\hat{x}_i, G(\hat{\mathbf{p}})] | \psi \rangle &= \langle \mathbf{p} | \hat{x}_i G(\hat{\mathbf{p}}) - G(\hat{\mathbf{p}}) \hat{x}_i | \psi \rangle \\
&= i \frac{\partial}{\partial p_i} \langle \mathbf{p} | G(\hat{\mathbf{p}}) | \psi \rangle - G(\mathbf{p}) \langle \mathbf{p} | \hat{x}_i | \psi \rangle \\
&= i \frac{\partial}{\partial p_i} [G(\mathbf{p}) \langle \mathbf{p} | \psi \rangle] - i G(\mathbf{p}) \frac{\partial}{\partial p_i} \langle \mathbf{p} | \psi \rangle \\
&= i \frac{\partial G(\mathbf{p})}{\partial p_i} \langle \mathbf{p} | \psi \rangle \\
&= \langle \mathbf{p} | i \frac{\partial G(\hat{\mathbf{p}})}{\partial p_i} | \psi \rangle
\end{aligned} \tag{6}$$

Since this holds for an arbitrary state ψ and an arbitrary \mathbf{p} , we have the operator statement

$$[\hat{x}_i, G(\hat{\mathbf{p}})] = i \frac{\partial G(\hat{\mathbf{p}})}{\partial p_i} , \tag{7}$$

which is the result that we were looking for.